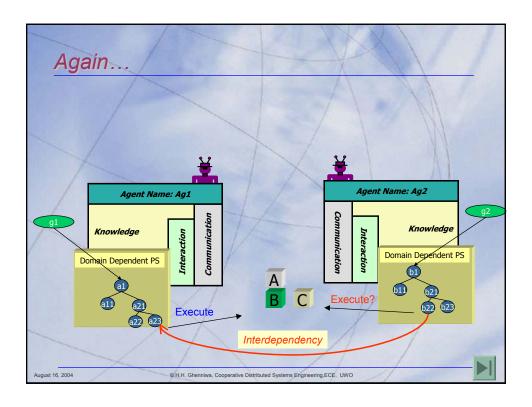
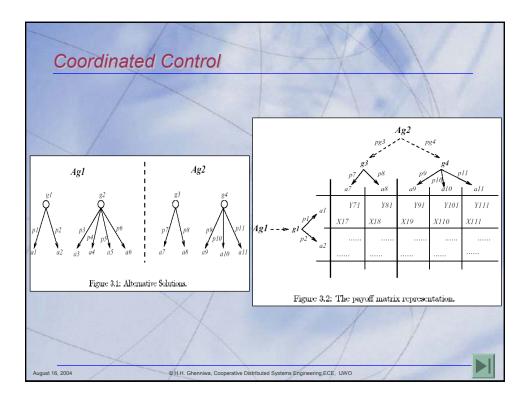
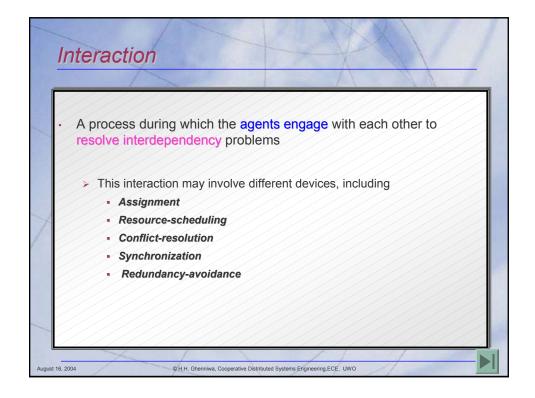


- How to design a coordination solution for different interdependency problems? - How to model coordination at -> Reasoning level -> Action level August 16, 2004 Other Gherniva. Cooperative Distributed Systems Engineering ECE, UWO 2



PAgust 16, 2004 • A set of • decision points for coordinated control • interaction devices collectively deal with the interdependency problem • Main objectives: • reduce and resolve the problems associated with interdependency • To deal with the dynamic characteristics of the environment • intelligence and rationality are employed • Intelligence is a set of heuristics related to the nature of the type of interdependency and the application domain • Rationality is the ability of the agent to analyze • Why, when, and which coordination solution is appropriate according to some performance measure





Types of Interaction Devices - Ghenniwa's

- Assignment Device
 - Capability and the decomposition interdependencies share similar characteristics
 - They are related to goals that cannot be achieved by the agent

An agent might solicit assistance from other agents

The assistance can have the form of delegating an appropriate agent to achieve the goal

- Resource Scheduling Device
 - > The major problem due to resource interdependency is
 - How to <u>assign</u> an authority for the agent over a resource for a specific interval of time

A solution to this problem might require the agent to negotiate with the other competing agents

Negotiation is the process of reaching an agreement

August 16, 2004

© H.H. Ghenniwa, Cooperative Distributed Systems Engineering, ECE, UWO

-/

Interaction -Ghenniwa's

- Conflict Resolution Device
 - Conflicting interdependency are due to <u>hard incompatibility</u> between the interest of an agent and some other agents (opponents).

A solution to this problem might require the agent to negotiate with its opponents

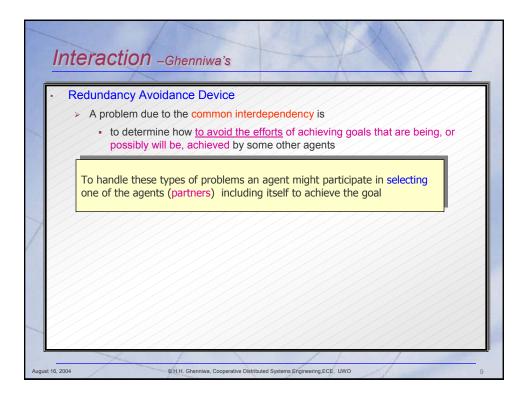
- Synchronization Device
 - A problem due to the simultaneous interdependency between agents (colleagues) is
 - determining how to <u>assign a common time frame</u> to <u>achieve the corresponding</u> goals

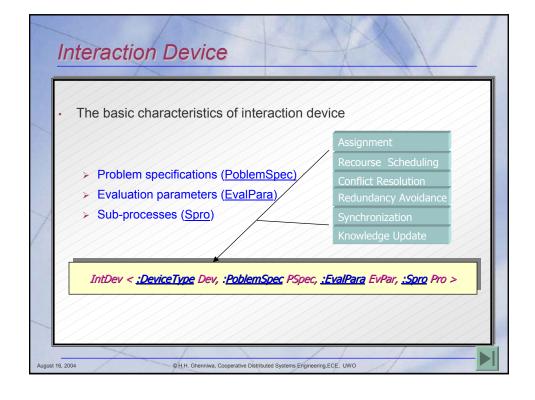
A negotiation based synchronization device can be used by the agents to reach an agreement about a common time frame

August 16, 200

© H.H. Ghenniwa, Cooperative Distributed Systems Engineering, ECE, UWO

8





The Assignment Device

- The basic characteristics
 - Problem specifications

goal, desired-satisfying-time

To deal with goal quality

$$G_c = \langle g, q^*, \delta q \rangle$$

Evaluation parameters

(goal class, local-schedule of the potential contractors)

Focused contracting:

(combination of Modeling and Soliciting approaches)

Sub-processes

The decision (selection) process

August 16, 2004

© H.H. Ghenniwa, Cooperative Distributed Systems Engineering, ECE, UWO

- 1

Negotiation-Based Devices

- Negotiation is <u>the search</u> for an <u>agreement</u> between incompatible desires of different agents
 - Negotiation <u>can be used</u> to determine the appropriate solution for resource-scheduling; conflict-resolution; synchronization; redundancy-avoidance

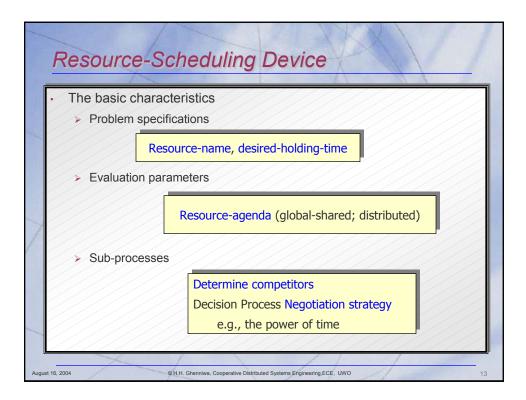
$$[HG \rightarrow Why?]$$

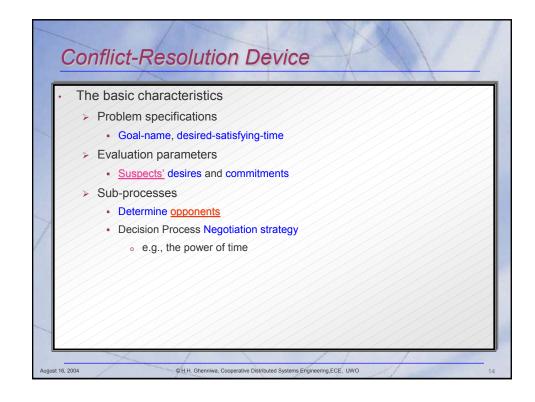
- Negotiation strategy depends on the degree of incompatibility
 - Hard
 - o for resource and conflicting interdependencies
 - Mild
 - o for simultaneous interdependency
 - Soft
 - o for common interdependency

August 16, 2004

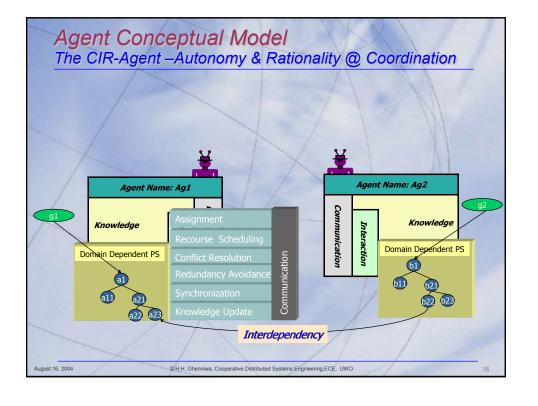
© H.H. Ghenniwa, Cooperative Distributed Systems Engineering, ECE, UWO

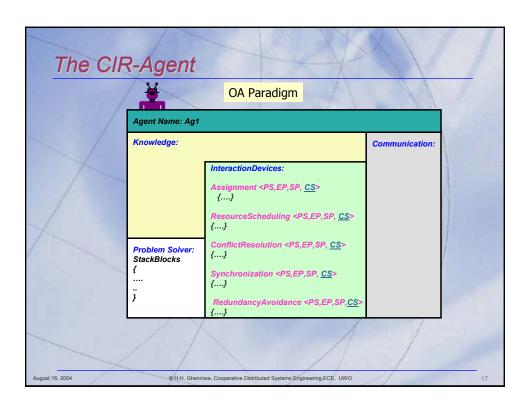
12

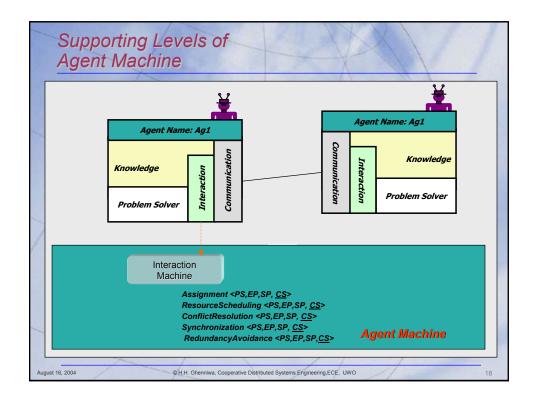


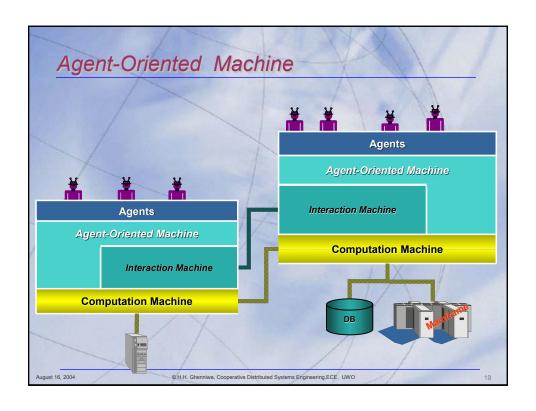


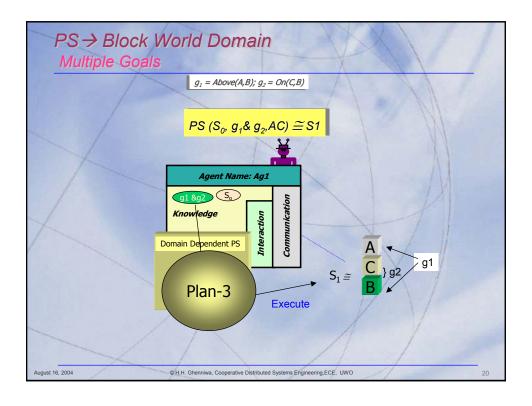
Synchronization Device The basic characteristics Problem specifications Goal-name, desired-time-frame Evaluation parameters Colleagues' desires and commitments Sub-processes Decision Process, Negotiation strategy: e.g., the power of time only when it is feasible to generate a counter offer

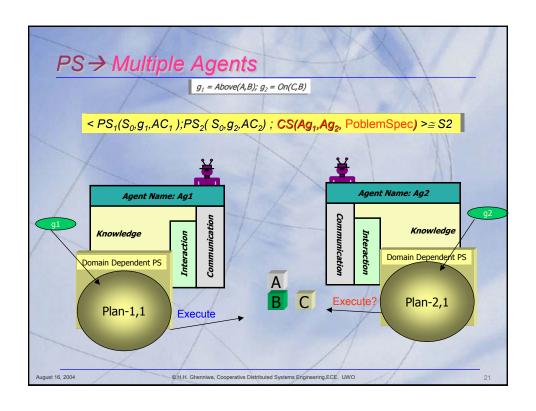


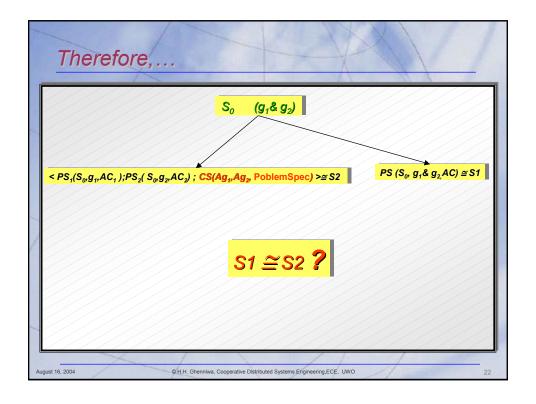


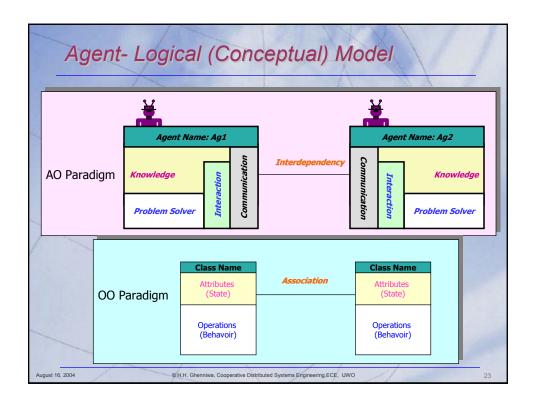


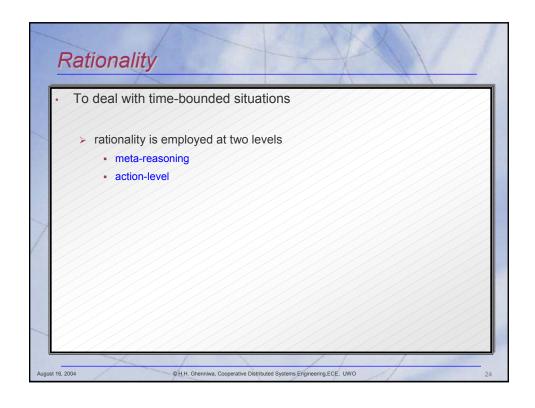












Meta-Reasoning Rationality

- The <u>selection of appropriate</u> heuristics for interaction devices
 - > The ability of the agent to evaluate the importance of the heuristics Which?
 - ➤ The dynamic nature of the performance structure of rationality When?
 - The rational behavior of the agent (e.g. minimizing performance measure) Why?

August 16, 2004

H.H. Ghenniwa, Cooperative Distributed Systems Engineering, ECE, UW

. . .

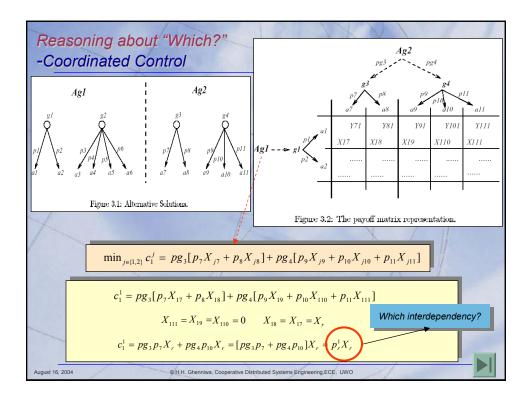
The Pre-Interaction:

- Reasoning about "Which"
 - > to identify the type of interdependencies and
 - to determine the agent's belief about their existence
- Reasoning about "How"
 - > to rationally anticipate the characteristics of the interaction devices
- The decision criterion
 - > to select a solution which satisfies some objective function
 - e.g., minimize the expected complexity

August 16, 2004

© H.H. Ghenniwa, Cooperative Distributed Systems Engineering, ECE, UWO

26



Reasoning about "Which?" -Coordinated Control

- -Coordinated Control
- This representation, however, has the following assumptions attached:
 - <u>Closure</u>: the state of the world can only be affected through the execution of the agents' actions.
 - <u>Influence</u>: during the process of selecting a domain action, each agent is concerned with the <u>influence[1]</u> of the other agents on the world domain rather than on their <u>`mental state'</u> regarding goals[2].
 - [1] This influence is represented in terms of the long term approximation (the agent's mental state) of coordination knowledge.
 - [2] The other <u>agents' mental state regarding their goals</u> is the concern of the interaction devices.

Reasoning about "How?" Interaction Device — Autonomy & Rationality @ Coordination Characteristics of the Assignment Device are determined by: The number of the potential participants The upper time-bound and solution-quality The rationality perspective: Optimal vs. Satisficing Strategies Bounded-optimality Bounded-duration

