

*ES595a - Advanced Topics in
Software & Systems Design
Cooperative Distributed Systems
Engineering:
Technologies & Applications*



W03: Agent-Orientation



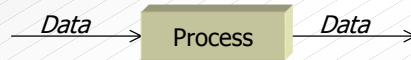
Outlines

- AO vs. Others
- AO: Coordinated, Intelligent Rational Agent

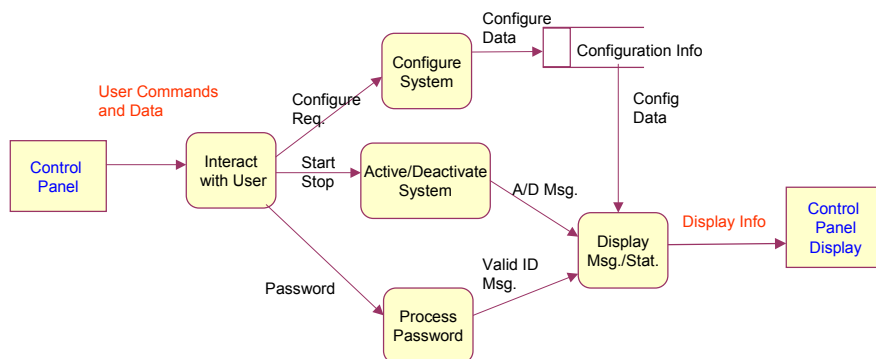
CIR-Agent Model

Functional Oriented

- The system functionality is described in terms of
data transformation process



Functional Oriented Approach

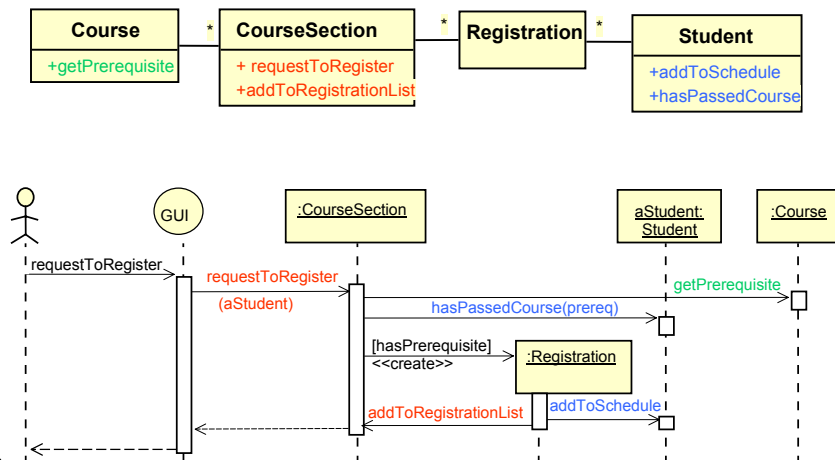


Object Oriented Paradigm

- The system functionality is described in terms of

A set of *interoperating objects*

Sequence Diagram Example



Agent-Orientation –Ghenniwa's

- Agent-orientation is the next generation for
 - software engineering paradigms
 - programming methodologies, and
 - computational modeling,

CDS: Design Concepts⁺⁺ Recall...

- ♦ Abstraction
- ♦ Refinement
- ♦ Modularity
- ♦ Information Hiding
- ♦ Interface
- ♦ Functional Independence
- ♦ Architecture
- ♦ Reusability

- ♦ Autonomy
- ♦ Coordination
 - ♦ Communication
 - ♦ Interaction
- ♦ Cooperation
- ♦ Adaptability

Agent View—Ghenniwa's

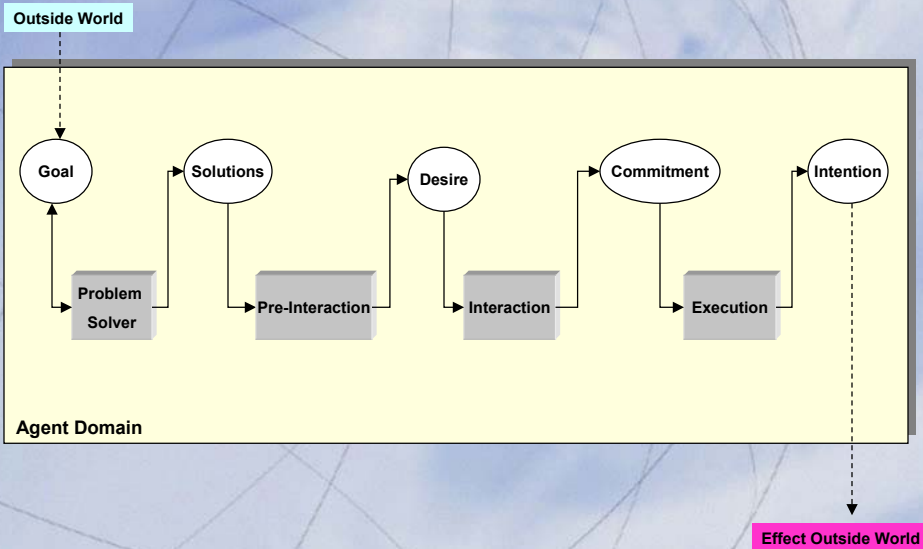
- A level of abstraction to **construct a computational** systems (agents)
 - that **inherent the agenthood features** including:
 - Primary
 - **coordination** and **rationality**
 - Secondary
 - **intelligence** and **learning**

They are useful for **distributed computation** in **open environments**

The Agent (System)—Ghenniwa's

- An agent as an **artifact** is an individual collection of **primitive components**
 - Each component is associated with a particular **functionality** supports a specific agent's **mental state** as related to its **goal**
 - A **particular arrangement** of the components **is required** to constitute an agent
 - This arrangement reflects **the pattern of the agent's mental state** as related to its reasoning to achieve a goal
 - The components can be **structured** to include:
 - **knowledge**
 - **Capabilities**
 - **problem-solving**
 - **communication**
 - **interaction**

Agent's Mental State



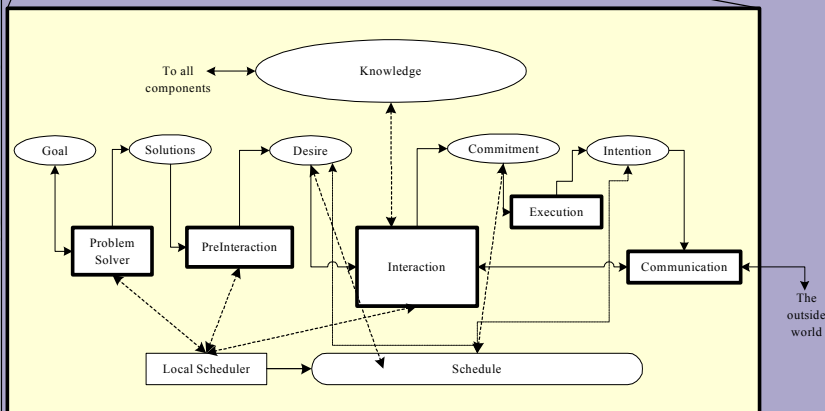
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The CIR-Agent Architecture



The agent's architecture is based on its mental-state regarding achieving its goal(s)

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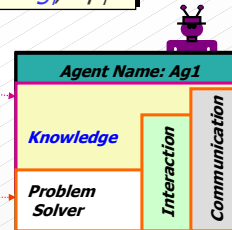
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The CIR-Agent Model

- An agent is an entity which possesses knowledge and capabilities;

$$Ag_i = \langle Kg_i, Cp_i \rangle$$

- Knowledge (Kg_i)
 - domain-dependent
 - self-model
 - others-models
- Capabilities (Cp_i)
 - Reasoning
 - problem-solving a
 - interaction
 - Communication



The Mental-State

- the agent's internal structural representation, at a given **instance of time**, for
 - **Goal**: goal-; solution-; desire-; commitment-; intention-state
 - **Reasoning** activities toward achieving a goal:
 - Problem-solving; pre-interaction; interaction; execution
 - **Time**
 - **Future**: virtual-time line (*local-schedule*)
 - **Current**: real-time clock
 - **Past**: virtual-time line associated with local-view (*local-history*)
 - **Local view** of the world
 - **Coordination** knowledge
 - **beliefs** related to the interdependency problems

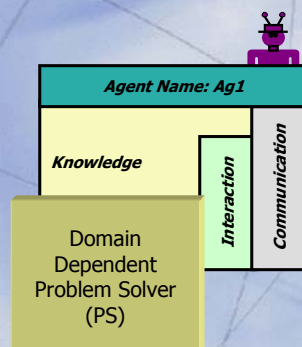
Implementation Assumptions!

- **No specific** assumptions need to be made on the detailed design of the agent components
 - Therefore, the components **can be developed and implemented** using object oriented or functional oriented approach,

provided
the **designer conceptualizing** a specific **architecture of the agent**

- In other words, object oriented technology for example, can be used to **enable agent-based technology**,
 - but agenthood features such as coordination and cooperation required by agents is not currently supported within OO technology

The Problem-Solver: Domain Dependent



What is a problem solver?

$PS \in \{\text{Car Assembly, Information Gathering, Object-Tracker, ...}\}$

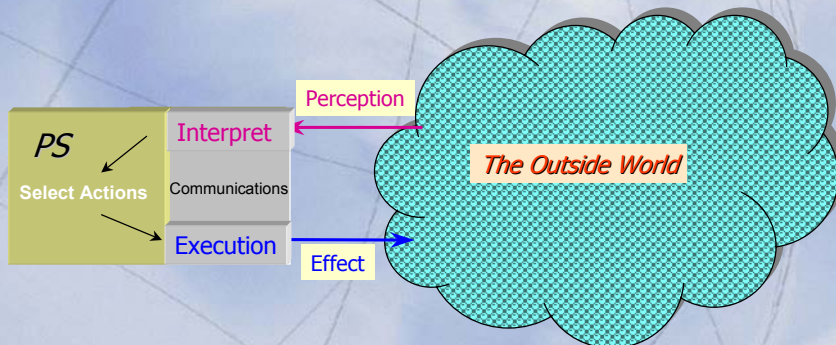
The Problem-Solver

- Goal-driven approach
 - more appropriate for cooperative distributed systems

$$PS: G_i \times AC_i \times W_i^t \rightarrow S_i^g$$

- G_i : set of Ag_i 's goals
 - AC_i : set of Ag_i 's domain actions
 - W_i : set of Ag_i 's world history
 - S_i^g : set of Ag_i 's solutions for $g \in G_i$
- Ps: local-control over achieving a domain goal
 - irresponsible for domain-actions associated with interdependency problem

$PS \leftrightarrow$ The Outside World

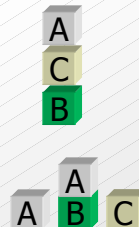


PS Autonomy

1. Perception: <Action-descriptor>
 - *Action=<Action-Descriptor, Action-Body>*
 - Static, Closed-World Assumption
 - PS: Identify Action-body
2. Perception: <State, Action-descriptor>
 - *Action=<Action-Descriptor, Preconditions, Action-Body>*
 - Dynamic, Closed World Assumption
 - PS: Identify Action-Body
 - React to the current state of World
3. Perception: <State, Goal>
 - *Action=<Action-Descriptor, Preconditions, Action-Body, Postconditions>*
 - Dynamic, Open Environment
 - PS: Identify Possible Course of Actions to achieve Goal

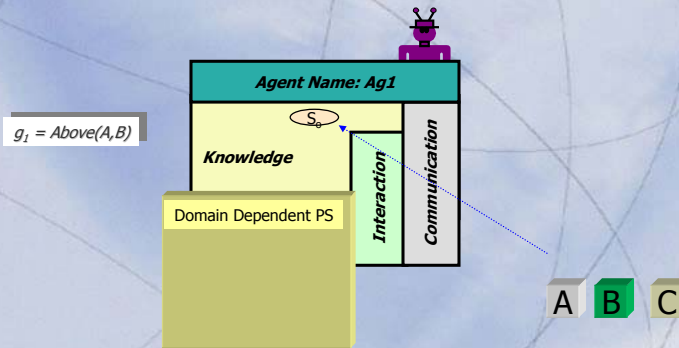
PS → Block World Domain

- Problem Solving:
 - the *domain-dependent role* of the agent
- Representation
 - e.g., state-based model
 - *World: <Domain-Objects, Relationships>*
 - *Action: State → State*
 - Example
 - $S_1 = on(A,C); S_2 = On(C,B)$
 - Actions: $a_1 = Puton(A,B);$



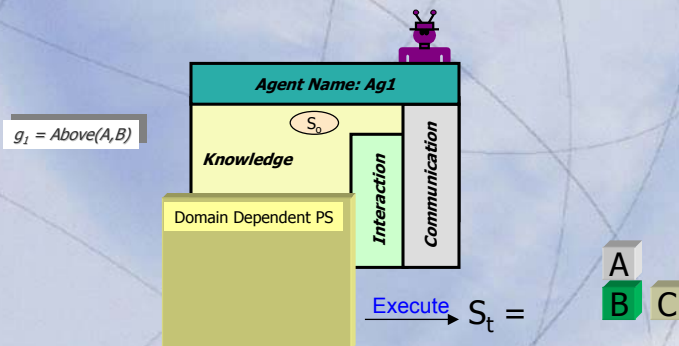
PS → Block World Domain

Single Goal



PS → Block World Domain

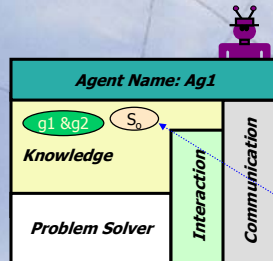
Single Goal



PS → Block World Domain

Multiple Goals

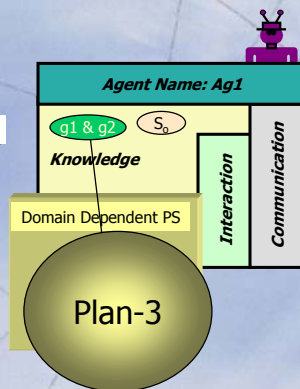
$g_1 = \text{Above}(A,B); g_2 = \text{On}(C,B)$



PS → Block World Domain

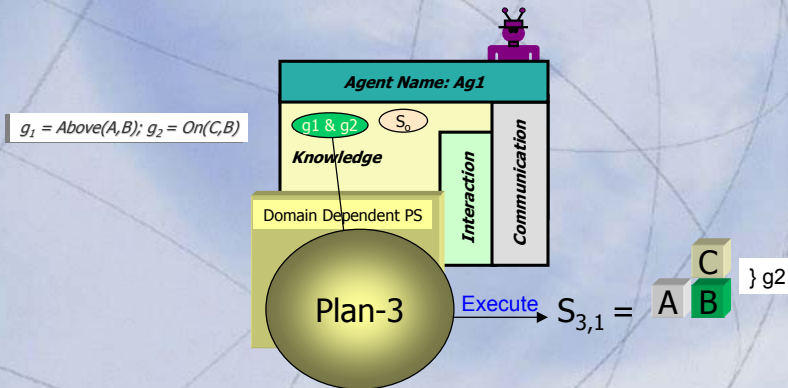
Multiple Goals

$g_1 = \text{Above}(A,B); g_2 = \text{On}(C,B)$



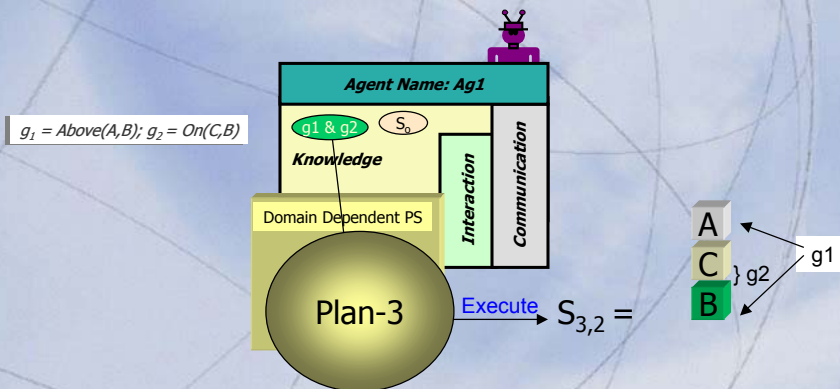
PS → Block World Domain

Multiple Goals



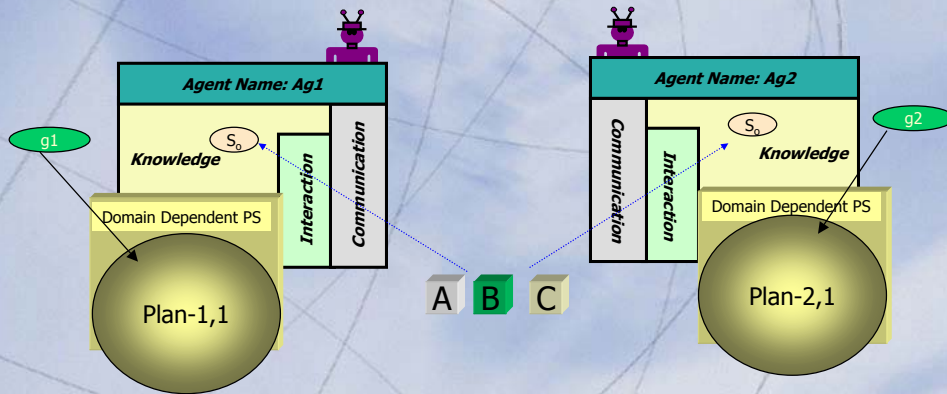
PS → Block World Domain

Multiple Goals



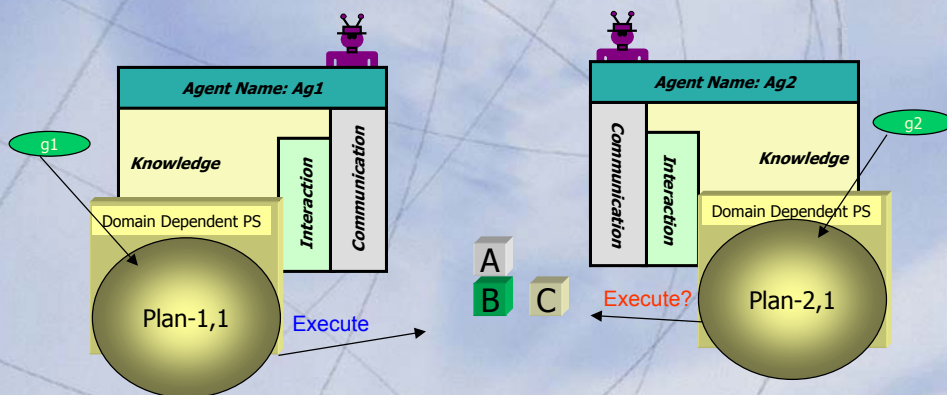
PS → Multiple Agents

$g_1 = \text{Above}(A,B); g_2 = \text{On}(C,B)$

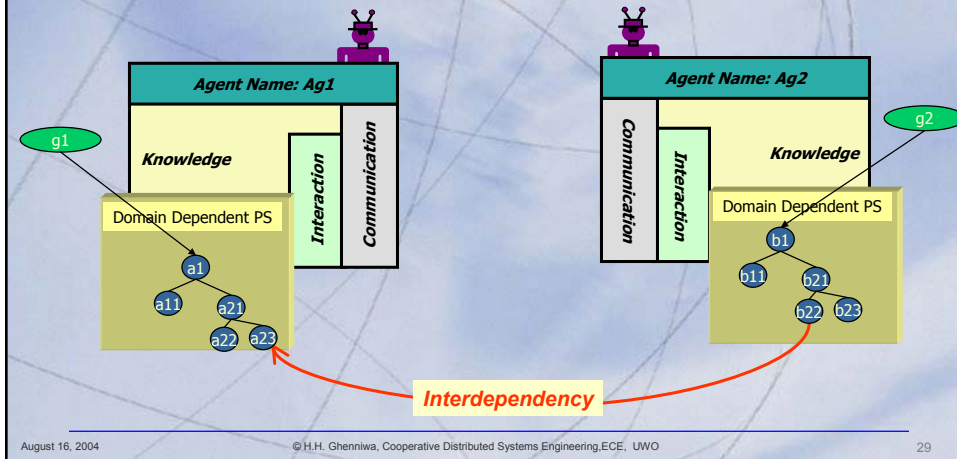


PS → Multiple Agents

$g_1 = \text{Above}(A,B); g_2 = \text{On}(C,B)$



PS → Multiple Agents Interdependency...



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Interdependency – Ghenniwa's

- Interdependencies are **goal-relevant relationships** among **actions** performed by various agents
 - For instance, Ag_1 attempts to achieve a goal that is **beyond its capability**, but it can be achieved with the help of Ag_2
 - Another kind interdependency that may exist between the agents is when each has a goal that can only be achieved through the use of a **'shared' resource** (e.g., a printer in the Lab)

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Modeling Interdependency Types—Ghenniwa's

Interdependency types Include:

- **Capability** interdependencies
 - **Decomposition** interdependencies
- **Interest** interdependencies
 - Conflict
 - Common
 - Simultaneous
 - Contradict
- **Resource** interdependencies
- **Knowledge** interdependencies

Modeling Interdependency —Ghenniwa's

- **Interdependency Types**
 - **Capability interdependencies**
 - are related to the agent's **bounded capability** of achieving goals
 - **Decomposition interdependencies**
 - are related to the agent's **decomposition of goals** into sub-goals, where achieving some of these sub-goals might be beyond its capability ---non self-containment.
 - **Knowledge interdependencies**
 - are related to the **required knowledge items** of the domain actions that **might be affected** by other agents.

Modeling Interdependency (Cont.)

- **Interdependency Types** (cont.)
 - **Interest interdependencies**
 - are related to the types of interrelationships that exist between **any pair of different agents' goals**.
 - These interrelationships include
 - **contradict**
 - **conflict**
 - **common**
 - **simultaneous**
 - **Resource interdependencies**
 - are related to the agents' domain actions that require **shared resources**
- **Uncertainty about Interdependencies**